

1. Definition of stochastic processes: (Kolmogoro Extension Theorem)

Given a random function $F: \mathcal{X} \rightarrow \mathcal{Y}$

For any finite sequence $x_{1:n} = (x_1, \dots, x_n)$, $\forall n \in \mathbb{N}$

$$y_{1:n} = (F(x_1), \dots, F(x_n))$$

① Exchangeability: for any permutation $\pi(x_{1:n})$ and $\pi(y_{1:n})$

(permutation invariance) $P_{x_{1:n}}(y_{1:n}) = P_{\pi(x_{1:n})}(\pi(y_{1:n}))$ ← Marginals remain as the same

② Consistency: for $1 \leq m \leq n$

$$P_{x_{1:m}}(y_{1:m}) = \int P_{x_{1:n}}(y_{1:n}) dy_{m+1:n}$$

An instantiation: $P_{x_{1:n}}(y_{1:n}) = \int P(f) P(y_{1:n} | f, x_{1:n}) df$ (1)

more specifically: $P_{x_{1:n}}(y_{1:n}) = \int P(f) \prod_{i=1}^n N(y_i | f(x_i), \sigma^2) df$

Gaussian Process (GP): $f \sim GP(\mu(x), k(x, x'))$

2. Neural Processes:

Introduce an auxiliary variable z :

Rewrite $F(x) = g(x, z)$, g is a NN, g is stochastic NN

We get a generative model: (latent z)

$$P(z, y_{1:n} | x_{1:n}) = P(z) \prod_{i=1}^n N(y_i | g(x_i, z), \sigma^2) \quad (2)$$

yields $P(z | x_{1:n}, y_{1:n})$

3. Variational Auto-Encoder:

$$\log P(y_{1:n} | x_{1:n}) \geq E_{q(z | x_{1:n}, y_{1:n})} \left[\sum_{i=1}^n \log P(y_i | z, x_i) + \log \frac{P(z)}{q(z | x_{1:n}, y_{1:n})} \right]$$

log evidence

Encoder $q(z|x_{1:n}, y_{1:n})$

Decoder $P(y_i|z, x_i)$

$$\begin{matrix} x_{1:n} \\ y_{1:n} \end{matrix} \xrightarrow{\begin{matrix} \mu_z \\ \sigma_z^2 \end{matrix}} z$$

Split data set: Context set $\{x_{1:m}, y_{1:m}\}$
target set $\{x_{m+1:n}, y_{m+1:n}\}$

$\log P(y_{m+1:n}|x_{1:n}, y_{1:m}) \geq$

$$E_{q(z|x_{1:n}, y_{1:n})} \left[\sum_{i=m+1}^n \log P(y_i|z, x_i) + \log \frac{P(z|x_{1:m}, y_{1:m})}{q(z|x_{1:n}, y_{1:n})} \right]$$

Encoder $q(z|x_{1:n}, y_{1:n})$, using both context and target sets

Decoder $P(y_i|z, x_i)$, only decodes target set

Replace $P(z|x_{1:m}, y_{1:m})$ with a data driven prior
 $q(z|x_{1:m}, y_{1:m})$

At testing, all observations $\{x_{1:n}, y_{1:n}\}$ are utilized to
construct $q(z|x_{1:n}, y_{1:n})$

Make prediction at x^* by

$$P(y^*|x^*, y_{1:n}, x_{1:n}) = \int q(z|x_{1:n}, y_{1:n}) \cdot N(y^*|g(x^*, z), \sigma^2) dz$$

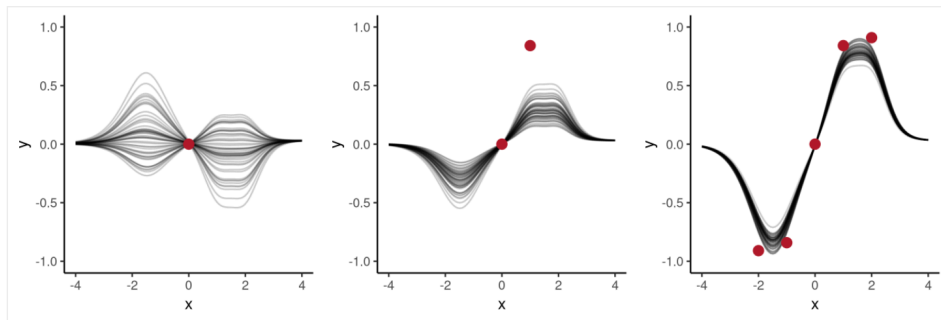
Meta learning: learn task level information

amplitude
↓
sinusoid Regression: $y = f(x) = a \sin(x)$
a function class $\{f \in \mathcal{M}\}$

For example: 1. $a \sim U[-2, 2]$

2. sample (x_i, y_i) s from curve $y = a \sin(x)$

3. At each training iteration, split (x_i, y_i) s into context and target sets to do optimization



$a=1$